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Nominal Data

Model	EG1R480450B	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2810
Power consumption	W	7011
Current draw	A	9.97
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

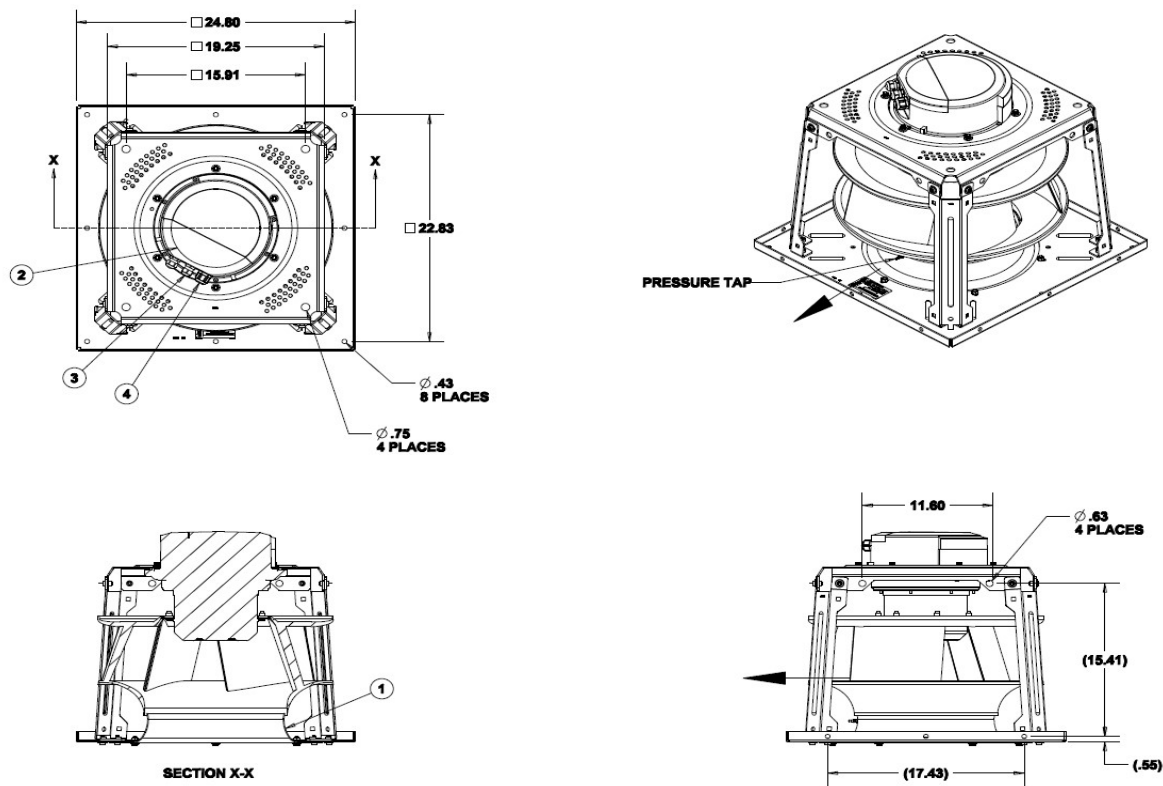
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	108 lb (49 kg)
Nominal Impeller Size	17.7 in (450 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	- Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6.4 - Motor current limitation - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection - Vibration sensor
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

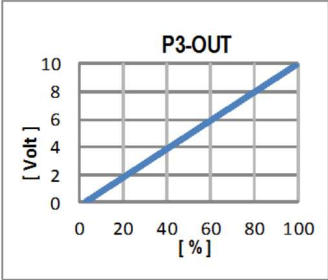
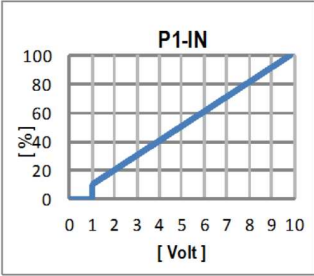
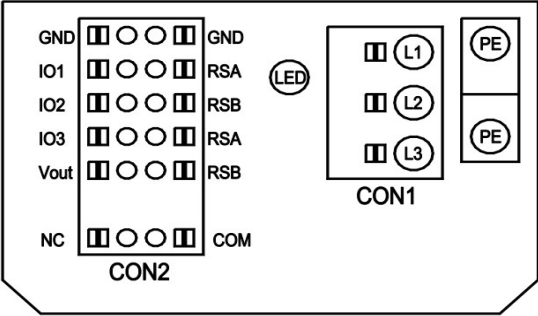
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 240
2	Terminal cover tightening torque: 26.6± 2.7 in-lbs (3±0.3 Nm)
3	Cable diameter: 0.16-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm)
4	Cable diameter: 0.2-0.55 in (5-14 mm) Cable gland tightening torque: 53.1±8 in-lbs (6±0.9 Nm)
	Note: Please contact ebm-papst if conduit is required
	Note: In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79500-2-4039 (not included in scope of delivery)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

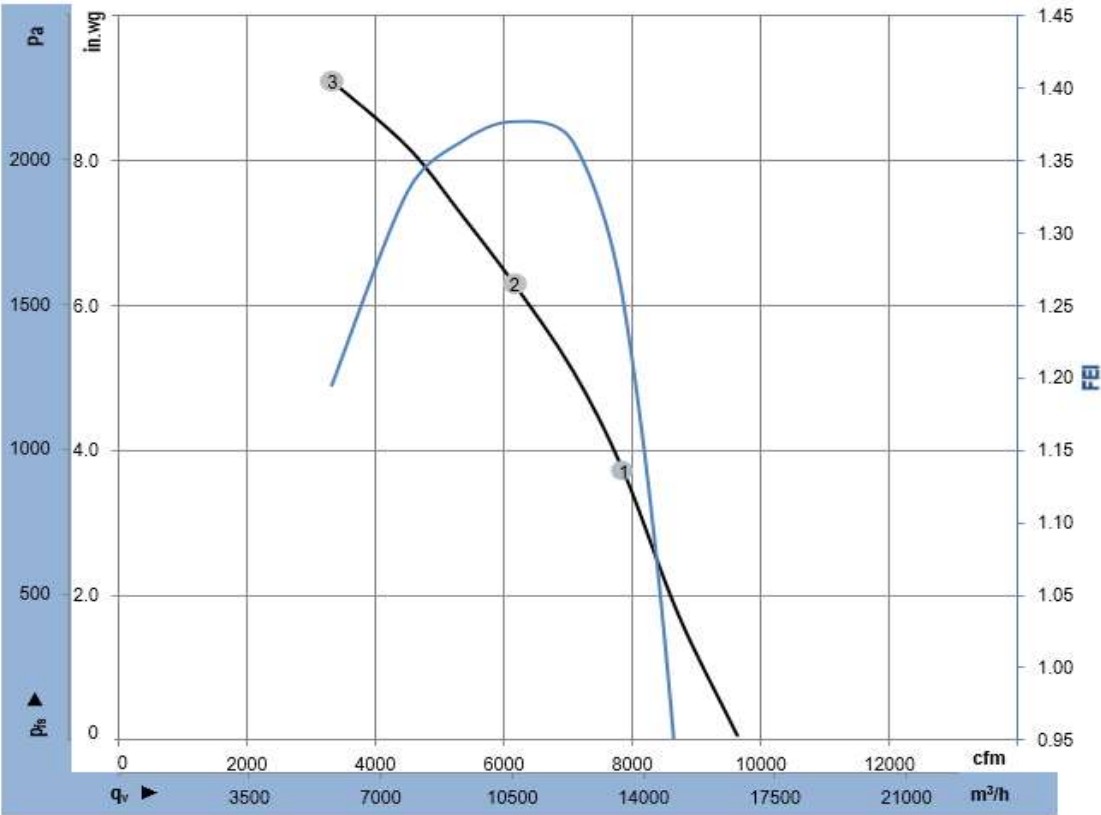
Electrical Interface



No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 VDC / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 VDC, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

Terminal assignment

configurable option																						
For further information and additional functions see EC Control Software, Fan-Set-App, or MODBUS Parameter Specification V6.3																						
CON2	configurable IO mode	electrical specification	MODBUS Register for IO mode configuration	functions: normal / inverse	source: set value	D101 [...]	D147 [...]	D104 [...]	D12E [...]	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	D130 [0]	D130 [1]	D130 [2]	D130 [5]	D00C [1]	D130 [4]			
					source: sensor value																	
					switch: parameter set: #1 / #2																	
					switch: control function: heating (pos.)																	
	switch: direction of rotation: cw / ccw																					
	switch: set value source																					
	switch: fan enable / disable																					
	signal: tach out																					
	signal: diagnostics out																					
	signal: fan modulation level %																					
signal: actual speed																						
signal: system modulation level %																						
signal: remote control output 0-10V																						
signal: remote control output 0-10V																						
pulse input for auto-addressing																						
pulse output for auto-addressing																						



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	2816	5981	8.6	7870	3.7	1.25
2	3~	460	60	2815	6960	9.9	6164	6.3	1.38
3	3~	460	60	2817	6397	9.1	3335	9.1	1.20

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.